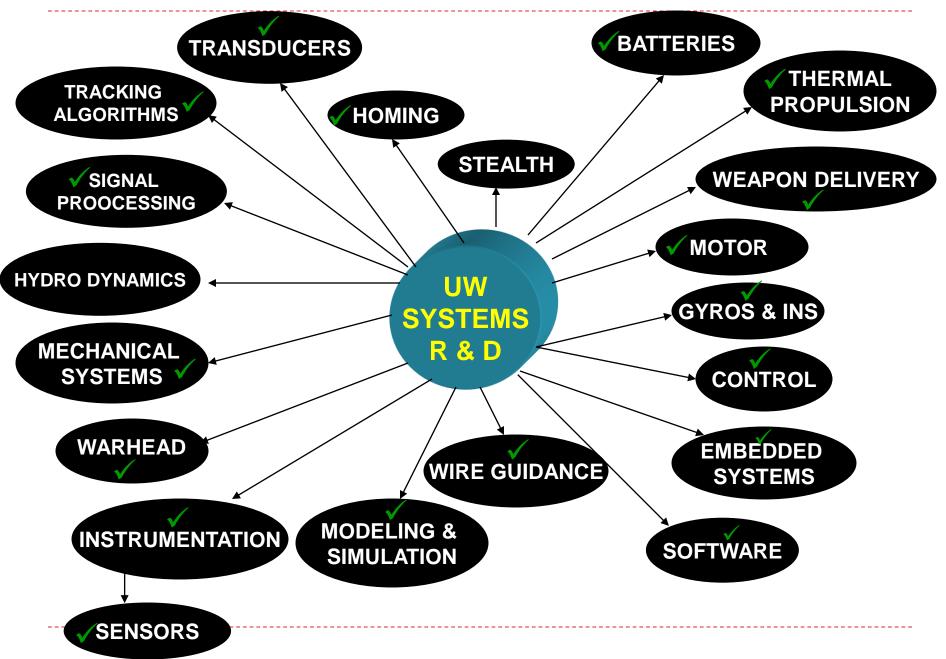
PERSPECTIVE ON TORPEDOES



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- Torpedoes Wish list
- Performance improvements Implications
- Hydro dynamics, Propulsion and Homing
- Development Process
- Indigenous efforts and way ahead

TORPEDO SYSTEMS DEVELOPMENT



Torpedoes – Wish list

- Maximise Range (Thermal Prop; CCTS)
- Depth Operation : 800 m + (New Materials)
- Maximise speed without compromising homing
- Maximising homing range with ACCM
- Homing capability for littoral waters
- Torpedo stealth (IMP, Hydrodynamic profile)
- Wire guidance (Long Range fibre optic communications)
- Improved Sonars
- Insensitive , light weight & more lethal warhead.
- Super cavitating u/w missiles
- Torpedo integration with network centric ASW
- Use of COTS & Open architecture

PERFORMANCE IMPROVEMENT - IMPLICATIONS

LOW SELF NOISE

TRANSMISSION POWER

REDESIGN O

ISOLATORS IMPROVEMENT

INCREASE IN HOMING RANGE CALLS FOR

> EFFECTIVE ELECTRONICS AND SIGNAL PROCESSING

CHANGE IN OPERATIONAL FREQUENCIES

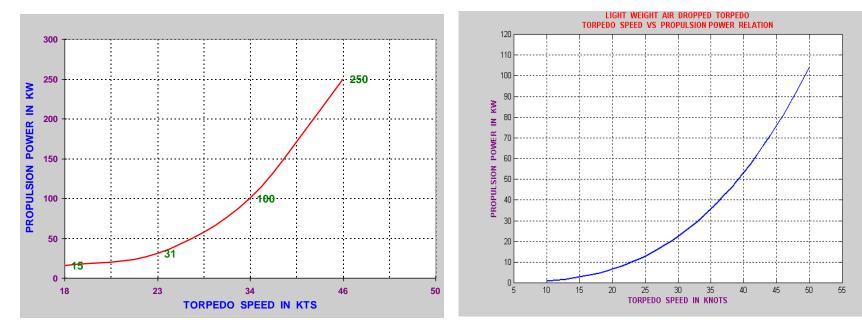
TRANSDUCER REDESIGN

Torpedo Propulsion Battery

Determines the Following Torpedo Parameters

- Torpedo Speed
- Torpedo Range
- Torpedo Endurance

As the Biggest Sub-system of the Torpedo by virtue of its Weight and Dimensions, determines the Torpedo Weight and Length



- Drag reduction techniques to be employed
- Increased Propeller efficiency
- Profile compliant motors
- Weight reduction of the battery
- Shells : weight reduction
- Reduction of self noise
- Incorporation of multi resonant sensors
- Light weight secondary battery technologies

Propulsion Motor : Requirements

- High endurance
- High Starting Torque
- Direct Switching from battery
- Higher Power to Weight Ratio
- High Efficiency
- Quick acceleration
- Incremental Speed Change
- Low Radiated Noise

Options

- Single shaft
- Contra rotating
- BLDC

Homing System – Current Technologies

- Mode of operation
 - Active
 - Passive
 - Mixed
- Detection based on digital signal processing techniques
- ACCM features
- Conformal Array with Wider look angle
- High Source level
- Online selection of PRI & PW

- Search for target
- Detection of target
- Echo validation
- > ACCM
- Generate target parameters



Homing System - Options

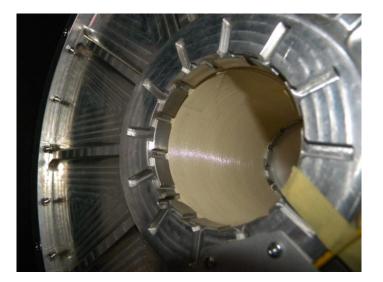
- Frequency of operation—space
 availability
- Area of coverage Array design
- Signal design Long range detection, ACCM
- Source level --- Acq. Range, Cavitation limit
- Active mode detection
- Passive mode detection
- Post detection schemes
- Adaptive threshold CFAR algorithms

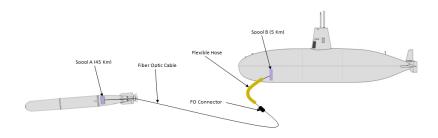
- Conformal array
 - Advantages
 - Look angle is more
 - Disadvantages
 - Ranges are lesser than Planar array
 - Reverberation problem due to more vertical beam width
- Planar array
 - Look Angle is less (< 100 deg horizontally)
 - Grating lobes in extreme beams
 - To avoid grating lobes, frequency is to be changed from center beam to extreme beam which demands higher bandwidth of sensors

Challenges in Homing system design

- Reduction of self noise
- Detection of target in presence of high reverberation levels
- Intelligent data processing to take online decision for better acquisition of target/ discrimination of target echo against decoys
- High probability of detection in an intense ACM environment
- Long range detection and classification of quiet, anechoic target submarine transiting at slow speeds.
- Multiple signals for optimal detection of target in Deep/Shallow waters and in the presence of decoys

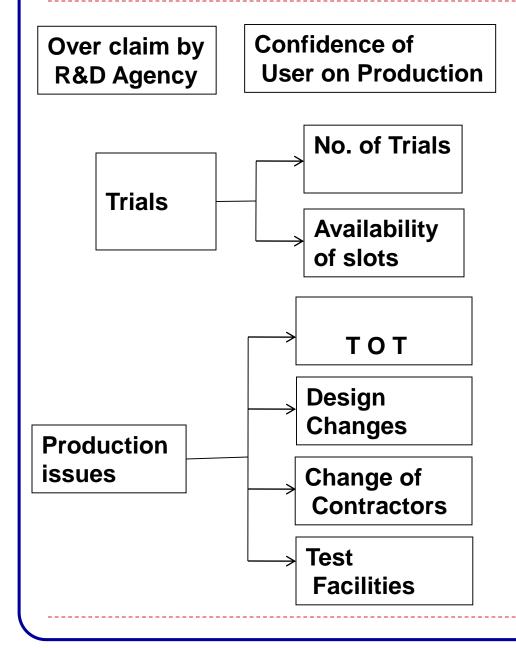
Fiber Optic Communication System



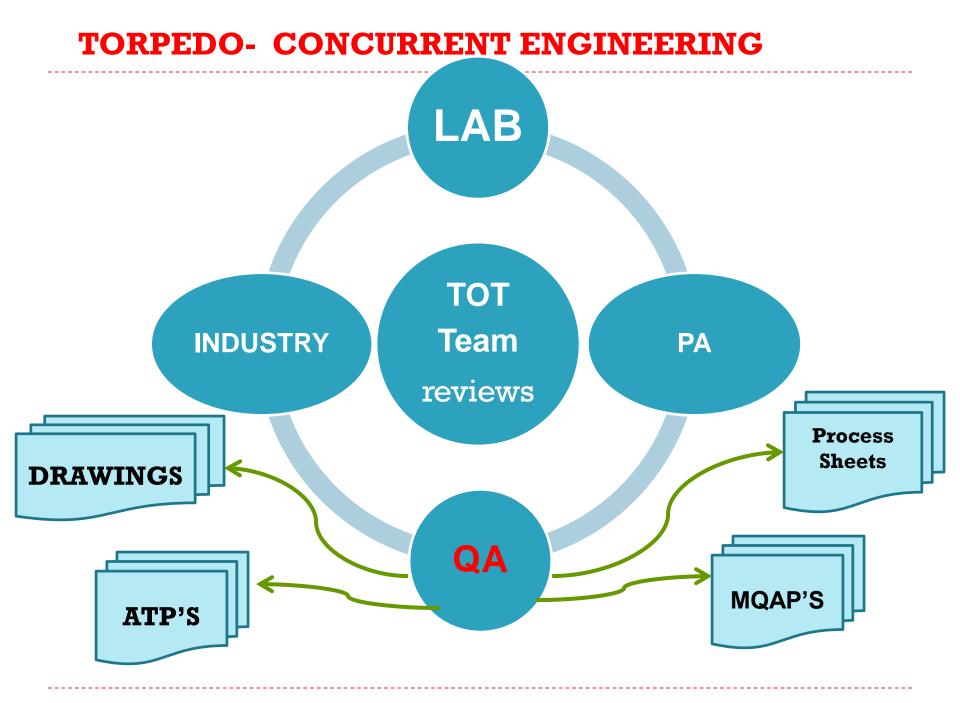


- Development of Fiber Optic System
 - Bend insensitive fibers
 - Polymer based jacketing
 - Winding technique
 - Packaging of the spool

Time delays - Solutions



- R & D Projects for Technology
 Development
- Dedicated Test Ranges
- More Simulation based trials
- Appreciation of product / technology by user
- Concurrent Engineering association of PA during R & D
- Pre-processing of Production
 order by User
- > Training



Light weight torpedoes

- Torpedo Advanced Light (TAL)
 - Air and ship launched
 - Completed all user trials satisfactorily
 - Inducted to Indian Navy





